

Factorization of multimeters: a unified view on nonclassical quantum phenomena

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Bad Honnef, April 10, 2026



- Main topic: Non-locality in [general probabilistic theories \(GPTs\)](#)

Main tool:

Factorization of [multimeters](#), i.e., collections of measurements.

- GPTs are a class of operational theories in which you can talk about preparations and measurement outcomes
- Insight: Multimeters can be written as channels between GPTs

General probabilistic theories

Measurement incompatibility as factorizations of multimeters

Steering as factorizations of multimeters

Bell non-locality as factorizations of multimeters

Extendability of tensors

General probabilistic theories

Decomposing quantum theory

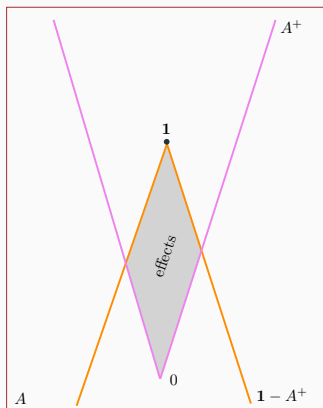
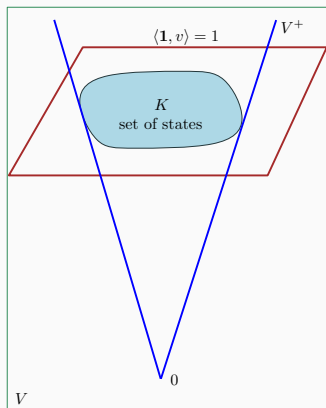
Set of quantum states:

$$\mathcal{S}(\mathbb{C}^d) := \{\rho \in \mathcal{M}_d(\mathbb{C})^{\text{herm}} : \rho \geq 0, \text{Tr}[\rho] = 1\}.$$

What do we need to define a set like this?

- In which (real) **vector space** do my states live? $\rho \in \mathcal{M}_d(\mathbb{C})^{\text{herm}}$
- What does it mean to be **positive**? $\rho \geq 0 \iff \rho \in \text{PSD}_d$
- Which **hyperplane** singles out the states among the positive elements? $\text{Tr}[\rho] = 1$

The parts of a GPT



- A **GPT** is a triple $(V, V^+, \mathbf{1})$, where V is a vector space, $V^+ \subseteq V$ is a cone, and $\mathbf{1}$ is a linear form on V ; $A = V^*$, $A^+ = (V^+)^*$, and $\mathbf{1} \in A^+$
- The set of states $K := V^+ \cap \mathbf{1}^{-1}(\{1\})$

Examples of GPTs (1/2)

Example: Classical mechanics

Any *classical system* is described by the triple $\text{CM}_d := (\mathbb{R}^d, \mathbb{R}_+^d, 1_d)$, $d \in \mathbb{N}$, where $1_d = (1, 1, \dots, 1)$. The classical state space is the simplex with d vertices S_d .

Example: Quantum mechanics

Quantum theory corresponds to the triple $\text{QM}_d := (\mathcal{M}_d(\mathbb{C})^{\text{herm}}, \text{PSD}_d, \text{Tr})$, $d \in \mathbb{N}$. The quantum state space is the set of density matrices $\mathcal{S}(\mathbb{C}^d)$.

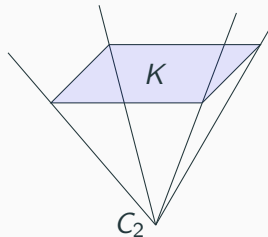
Examples of GPTs (2/2)

Example: g-bits

The *hypercube* GPT has the unit ball of ℓ_∞^n as a state space, $n \in \mathbb{N}$. It is described by the triple $\text{HC}_n := (\mathbb{R}^{n+1}, C_n, \mathbb{1})$, where

$$C_n = \{(x_0, x_1, \dots, x_n) \in \mathbb{R}^{n+1} : x_0 \geq \max_{i \in [n]} |x_i|\}$$

$$\mathbb{1}(x_0, x_1, \dots, x_n) = x_0.$$



Bipartite systems

Let $(V_A, V_A^+, \mathbb{1}_{V_A})$ and $(V_B, V_B^+, \mathbb{1}_{V_B})$ be two GPTs. How to construct a joint GPT?

- Joint vector space $V_{AB} := V_A \otimes V_B$, order unit $\mathbb{1}_{V_{AB}} := \mathbb{1}_{V_A} \otimes \mathbb{1}_{V_B}$
- For the cone V_{AB}^+ , we have in general infinitely many choices.

Definition (Minimal tensor product)

Let V_A^+ and V_B^+ be two cones. Their *minimal tensor product* is then defined as $V_A^+ \dot{\otimes} V_B^+ = \text{conv}\{x_A \otimes x_B \mid x_A \in V_A^+, x_B \in V_B^+\}$.

Definition (Maximal tensor product)

The *maximal tensor product* of two cones is the set $V_A^+ \hat{\otimes} V_B^+ = ((V_A^+)^* \dot{\otimes} (V_B^+)^*)^*$.

We are free to choose any tensor cone, i.e., any cone V_{AB}^+ such that

$$V_A^+ \dot{\otimes} V_B^+ \subseteq V_{AB}^+ \subseteq V_A^+ \hat{\otimes} V_B^+.$$

Examples of bipartite systems

- If one of the GPTs is CM_d , the resulting joint GPT is unique, since the tensor product of cones is unique as soon as one of them is simplicial [ALPP21]
- In quantum mechanics, $\text{PSD}_m \dot{\otimes} \text{PSD}_n$ are the positive semi-definite matrices that are separable and $\text{PSD}_m \hat{\otimes} \text{PSD}_n$ the ones that are block-positive (entanglement witnesses).
- Hence

$$\text{PSD}_m \dot{\otimes} \text{PSD}_n \subsetneq \text{PSD}_{mn} \subsetneq \text{PSD}_m \hat{\otimes} \text{PSD}_n$$

- The tensor product of two copies of HC_2 with the $C_2 \hat{\otimes} C_2$ as cone gives a theory with PR boxes (correlations that win the CHSH game perfectly).

Positive maps and channels

Let $(V_A, V_A^+, \mathbb{1}_{V_A})$ and $(V_B, V_B^+, \mathbb{1}_{V_B})$ be two GPTs.

- *Channels* are linear mappings $\Phi : V_A \rightarrow V_B$ that are positive, i.e., $\Phi(V_A^+) \subseteq V_B^+$, and normalization-preserving, i.e., $\mathbb{1}_{V_B}(\Phi(v)) = \mathbb{1}_{V_A}(v)$ for all $v \in V_A$.
- We may also denote the channel $\Phi : V_A \rightarrow V_B$ simply as a map $\Phi : K_A \rightarrow K_B$ between the state spaces of the GPTs.
- Let $\{e_i\}_i$ be a basis of V_A and let $\{\alpha_j\}_j$ a dual basis of A_A , i.e., $\alpha_j(e_i) = \delta_{ij}$. We can define a special tensor $\chi_{V_A} \in A_A^+ \hat{\otimes} V_A^+$ as

$$\chi_{V_A} = \sum_{i=1}^d \alpha_i \otimes e_i.$$

Lemma

Let $\xi \in K_B \hat{\otimes} K_A$. Then, there is a unique map $\Phi : A(K_A)^+ \rightarrow V(K_B)^+$ such that $\xi = (\Phi \otimes \text{id})(\chi_{V(K_A)})$ and $\Phi(\mathbb{1}_{K_A}) \in K_B$.

Effects and measurements

Effects are elementary yes-no-measurements, i.e.,

$$\mathcal{E} := \{\alpha \in A^+ : \mathbb{1} - \alpha \in A^+\}.$$

Definition

Let $(V, V^+, \mathbb{1})$ be a GPT with a state space K . A measurement (or *meter*) on K with $k < \infty$ outcomes is described by a channel $f : K \rightarrow S_k$.

We can decompose

$$f(\varrho) = \sum_{i=1}^k f_i(\varrho) \delta_i$$

for all $\varrho \in K$, where the f_i are effects summing to $\mathbb{1}$ and the δ_i are the vertices of the simplex. On the other hand, given k effects $f_1, \dots, f_k$ that satisfy $\sum_{i=1}^k f_i = \mathbb{1}$ one can use the above equation to define a channel from K to S_k .

We can define instruments as specific types of channels:

Definition

Let $(V_A, V_A^+, \mathbb{1}_{V_A})$ and $(V_B, V_B^+, \mathbb{1}_{V_B})$ be two GPTs with state spaces K_A and K_B , respectively. An instrument from K_A to K_B with k outcomes is described by a channel $\Phi : K_A \rightarrow K_B \dot{\otimes} S_k$.

Each k -outcome instrument Φ between K_A and K_B is characterized by a collection of operations $\Phi_1, \dots, \Phi_k$ such that $\sum_{i=1}^k \Phi_i$ is a channel from K_A to K_B which maps

$$\Phi(\varrho) = \sum_{i=1}^k \Phi_i(\varrho) \otimes \delta_i$$

for all $\varrho \in K_A$.

Definition

The *column stochastic GPT* is given by $(CS_{k,g}, CS_{k,g}^+, \mathbb{1}_{CS_{k,g}^1})$, where $CS_{k,g}$ is the vector space of real $k \times g$ -matrices whose column sums are equal, $CS_{k,g}^+$ is the cone of non-negative such matrices and $\mathbb{1}_{CS_{k,g}^1} : CS_{k,g} \rightarrow \mathbb{R}$ is a functional defined as $\mathbb{1}_{CS_{k,g}^1}(M) := \frac{1}{g} \text{Tr}[J_{k,g} M]$ for all $M \in CS_{k,g}$, where $J_{k,g}$ is the $k \times g$ -matrix of all ones. The state space of this GPT is the set of column stochastic $k \times g$ -matrices (non-negative $k \times g$ -matrices whose columns sum to one), which we denote by $CS_{k,g}^1$.

Definition

Let $(V, V^+, \mathbb{1})$ be a GPT with a state space K . A multimeter on K with g measurements, each with k outcomes, is described by a channel $f : K \rightarrow CS_{k,g}^1$.

Alternatively, we can also represent f as

$$f(\varrho) = \sum_{x=1}^g \sum_{a=1}^k f_{a|x}(\varrho) E_{a,x} = (f_{\cdot|1}(\varrho), \dots, f_{\cdot|g}(\varrho))$$

for all $\varrho \in K$. Here, the $E_{a,x}$ are matrix units and the $f_{a|x}$ are effects forming measurements $f_{\cdot|x}$.

Measurement incompatibility as factorizations of multimeters

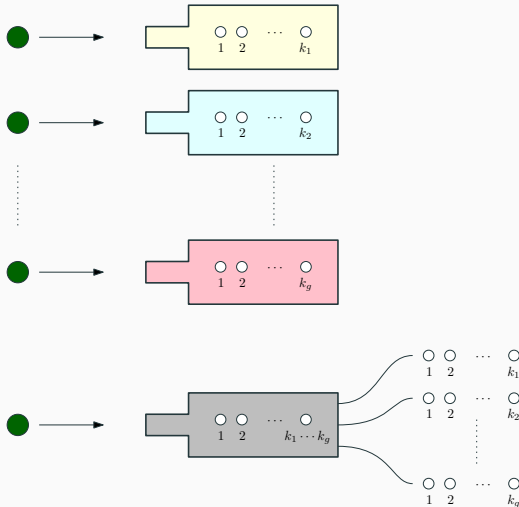
Compatible measurements

Definition

A multimeter $M = \{M_{\cdot|x}\}_{x \in [g]}$ of g measurements with k outcomes on K is compatible if there exists a single l -outcome measurement N on K and some conditional probability distribution $\nu = (\nu_{\cdot|b,x})_{b \in [l], x \in [g]}$ on $[k]$ such that

$$M_{a|x} = \sum_{b=1}^l \nu_{a|b,x} N_b$$

for all $a \in [k]$ and $x \in [g]$.

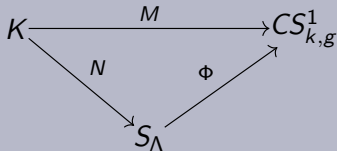


Compatibility as factorization

Theorem

Let $M = \{M_{\cdot|x}\}_{x \in [g]}$ be a multimeter of g measurements with k outcomes on a state space K . Then, the following are equivalent:

1. $(\text{id} \otimes M)(\chi_{V(K)}) \in K_{\varrho}^* \dot{\otimes} CS_{k,g}^1$ for some ϱ in the relative interior of K
2. M consists of compatible measurements
3. There exist a finite number of outcomes Λ , a measurement $N : K \rightarrow S_{\Lambda}$, and a channel $\Phi : S_{\Lambda} \rightarrow CS_{k,g}^1$ such that the following diagram commutes:



Recovers results from [Jen18]. Here, $K_{\varrho}^* := \{f \in A(K)^+ : f(\varrho) = 1\}$.

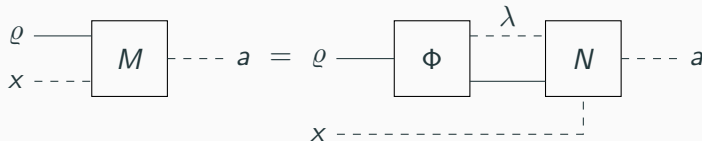
Compression of multimeters

Definition

Let $M = \{M_{\cdot|x}\}_{x \in [g]}$ be a multimeter of g measurements with k outcomes on a state space K_A . It is K_B -*simulable* if there exists a finite number of outcomes Λ , an instrument $\Phi : K_A \rightarrow K_B \dot{\otimes} S_\Lambda$ with operations $\Phi_\lambda : V(K_A)^+ \rightarrow V(K_B)^+$, and a multimeter $N = \{N_{\cdot|x,\lambda}\}_{x \in [g], \lambda \in [\Lambda]}$ of $g \cdot \Lambda$ measurements with k outcomes on K_B such that

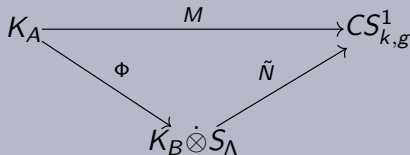
$$M_{a|x} = \sum_{\lambda=1}^{\Lambda} \Phi_\lambda^*(N_{a|x,\lambda})$$

for all $a \in [k]$ and $x \in [g]$. Generalizes an idea from [ISD+22].



Theorem

Let $M = \{M_{\cdot|x}\}_{x \in [g]}$ be a multimeter of g measurements with k outcomes on a state space K_A . Then M is K_B -simulable if and only if there exists a finite number of outcomes Λ , an instrument $\Phi : K_A \rightarrow K_B \dot{\otimes} S_\Lambda$ and a multimeter $\tilde{N} : K_B \dot{\otimes} S_\Lambda \rightarrow CS_{k,g}^1$ such that the following diagram commutes:



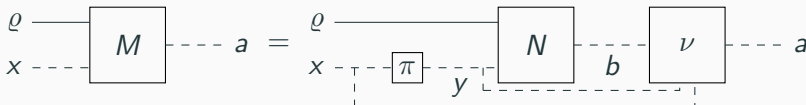
Classical simulation of multimeters

Definition ([FHL18])

Let $M = \{M_{\cdot|x}\}_{x \in [g]}$ be a multimeter of g measurements with k outcomes on a state space K . We say that M can be *classically simulated* (or is *classically simulable*) with a multimeter $N = \{N_{\cdot|y}\}_{y \in [r]}$ of r measurements with l outcomes on K if there exist conditional probability distributions $\pi = (\pi_{\cdot|x})_{x \in [g]}$ on $[r]$ and $\nu = (\nu_{\cdot|b,x,y})_{b \in [l], x \in [g], y \in [r]}$ on $[k]$ such that

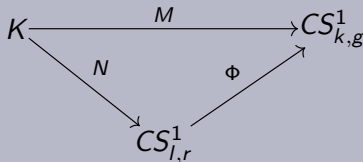
$$M_{a|x} = \sum_{y=1}^r \pi_{y|x} \sum_{b=1}^l \nu_{a|b,x,y} N_{b|y}$$

for all $a \in [k]$ and $x \in [g]$.



Theorem

A multimeter $M = \{M_{\cdot|x}\}_{x \in [g]}$ of g measurements with k outcomes on a state space K can be classically simulated with a multimeter $N = \{N_{\cdot|y}\}_{y \in [r]}$ of r measurements with l outcomes on K if and only if there exists a channel $\Phi : CS_{l,r}^1 \rightarrow CS_{k,g}^1$ such that the following diagram commutes:



Steering as factorizations of multimeters

Definition

Let $(V(K), V(K)^+, \mathbb{1}_K)$ be a GPT. An *assemblage* is a set $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ of states $\varrho_{a|x} \in K$ and conditional probability distributions $(q_{a|x})_{a \in [k]}$ for all $x \in [g]$ together with an average state $\bar{\varrho} \in K$ such that

$$\bar{\varrho} = \sum_{a \in [k]} q_{a|x} \varrho_{a|x} \quad \forall x \in [g].$$

Definition

Let $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ be an assemblage. Then, the assemblage admits an *LHS model* if there exist $\Lambda \in \mathbb{N}$, a set of states $\{\sigma_\lambda\}_{\lambda \in [\Lambda]}$, a probability distribution $(p_\lambda)_{\lambda \in [\Lambda]}$ and conditional probability distributions $(\nu_{a|\lambda, x})_{a \in [k]}$ for all $\lambda \in [\Lambda]$, $x \in [g]$, such that

$$q_{a|x} \varrho_{a|x} = \sum_{\lambda=1}^{\Lambda} \nu_{a|\lambda, x} p_\lambda \sigma_\lambda \quad \forall a \in [k], \forall x \in [g].$$

Assemblages as multimeters

We can associate to an assemblage a map $\Phi : (CS_{k,g}^*)^+ \rightarrow V(K)^+$ such that

$$\Phi(\mathbb{1}_{CS_{k,g}^1}) = \bar{\varrho}$$

$$\Phi(m_a^{(x)}) = q_{a|x} \varrho_{a|x} \quad \forall x \in [g], \forall a \in [k].$$

$m_a^{(x)} = \text{Tr}[E_{a,x} \cdot]$, where $E_{a,x}$ is a matrix unit with a 1 at (a, x) . If $\bar{\varrho}$ is in the relative interior of K , the dual map $\Phi^* : K_{\bar{\varrho}}^* \rightarrow CS_{k,g}^1$ is a multimeter.

Remark

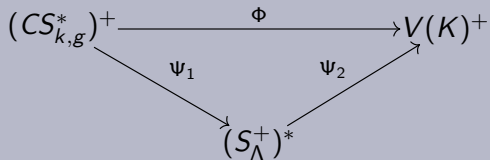
Warning: Unlike in quantum mechanics, an assemblage cannot always be seen as coming from measuring a bipartite state on one system.

Having an LHS model as factorization

Theorem

Let $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ be an assemblage with average state $\bar{\varrho} \in K$ and associated map $\Phi : (CS_{k,g}^*)^+ \rightarrow V(K)^+$ such that $\Phi(\mathbb{1}_{CS_{k,g}^1}) = \bar{\varrho}$. Then, TFAE:

1. $(\text{id} \otimes \Phi)(\chi_{CS_{k,g}^*}) \in CS_{k,g}^1 \dot{\otimes} K$
2. $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ has an LHS model
3. There exist a finite number Λ , and appropriate maps Ψ_1, Ψ_2 such that the following diagram commutes:



Classical simulation of assemblages

Definition

Let $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ be an assemblage with average state $\bar{\varrho} \in K$. We say that the assemblage can be *classically simulated* (or is *classically simulable*) by an assemblage $\{v_{b|y}, \sigma_{b|y}\}_{b \in [l], y \in [r]}$ with $\bar{\sigma} = \bar{\varrho} \in K$ if there exist conditional probability distributions $\pi = (\pi_{\cdot|x})_{x \in [g]}$ on $[r]$ and $\nu = (\nu_{\cdot|b,x,y})_{b \in [l], x \in [g], y \in [r]}$ on $[k]$ such that

$$q_{a|x} \varrho_{a|x} = \sum_{y=1}^r \pi_{y|x} \sum_{b=1}^l \nu_{a|b,x,y} v_{b|y} \sigma_{b|y}$$

for all $a \in [k]$ and $x \in [g]$.

Motivation: Applying a classically simulable multimeter on half of a bipartite state.

Classical simulation of assemblages as factorization

Theorem

Let $\{q_{a|x}, \varrho_{a|x}\}_{a \in [k], x \in [g]}$ be an assemblage with average state $\bar{\varrho} \in K$ and associated map $\Phi : (CS_{k,g}^*)^+ \rightarrow V(K)^+$ such that $\Phi(\mathbb{1}_{CS_{k,g}^*}) = \bar{\varrho}$. Then this assemblage is classically simulable by the assemblage $\{v_{b|y}, \sigma_{b|y}\}_{b \in [l], y \in [r]}$ with $\bar{\sigma} = \bar{\varrho} \in K$ if and only if there exist appropriate maps Ψ_1 and Ψ_2 such that the following diagram commutes:

$$\begin{array}{ccc} (CS_{k,g}^*)^+ & \xrightarrow{\Phi} & V(K)^+ \\ & \searrow \Psi_1 \quad \nearrow \Psi_2 & \\ & (CS_{l,r}^*)^+ & \end{array}$$

If $\bar{\varrho}$ is in the relative interior of K , the assemblage is classically simulable if and only if the multimeter $\Phi^* : K_{\bar{\varrho}}^* \rightarrow CS_{k,g}^1$ is classically simulable.

Bell non-locality as factorizations of multimeters

Bell behaviors

- Bipartite **Bell behavior**:

$$\text{Tr}[(M_{a|x} \otimes N_{b|y}) \varrho] = p_{a,b|x,y} \geq 0 \quad \text{with } a \in [k], b \in [l], x \in [g], y \in [r].$$

- Given multimeters $M : K_A \rightarrow CS_{k,g}^+$, $N : K_B \rightarrow CS_{l,r}^+$ and $\varrho \in K_A \otimes K_B$, $(M \otimes N)(\varrho)$ is in $CS_{k,g}^1 \hat{\otimes} CS_{l,r}^1$.
- The set of all no-signaling behaviors is in 1-to-1 correspondence with $CS_{k,g}^1 \hat{\otimes} CS_{l,r}^1$.

Definition

A Bell behavior $(p_{a,b|x,y})_{a \in [k], b \in [l], x \in [g], y \in [r]}$ can be described by an LHV model if there is a locally hidden variable $\Lambda \in \mathbb{N}$ and probability distributions q on $[\Lambda]$ and $(v_{\cdot|\lambda,x})$ on $[k]$, $(w_{\cdot|\lambda,y})$ on $[l]$ such that

$$p_{a,b|x,y} = \sum_{\lambda \in [\Lambda]} q_{\lambda} v_{a|\lambda,x} w_{b|\lambda,y}$$

for all $a \in [k]$, $b \in [l]$, $x \in [g]$, $y \in [r]$.

Theorem

$\Phi : (CS_{k,g}^+)^* \rightarrow CS_{l,r}^+$ with $\Phi(\mathbb{1}_{CS_{k,g}^1}) \in CS_{l,r}^1$ if and only if and there exist no-signaling probability distributions $(p_{a,b|x,y})_{a \in [k], b \in [l]}$ such that

$$\langle m_b^{(y)}, \Phi(m_a^{(x)}) \rangle = p_{a,b|x,y} \quad \forall a \in [k], \forall b \in [l], \forall x \in [g], \forall y \in [r]$$

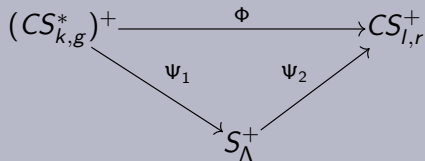
If $\Phi(\mathbb{1}_{CS_{k,g}^1}) = q$ is in the relative interior of $CS_{k,g}^1$, then $\Phi : (CS_{k,g}^1)_q^* \rightarrow CS_{l,r}$ is a multimeter.

Having an LHV model as factorization

Theorem

Let $\Phi : (CS_{k,g}^*)^+ \rightarrow CS_{l,r}^+$ with $\Phi(\mathbb{1}_{CS_{k,g}^1}) \in CS_{l,r}^1$. Then, the following are equivalent:

1. $(\Phi \otimes \text{id})(\chi_{CS_{k,g}}) \in CS_{l,r}^1 \dot{\otimes} CS_{k,g}^1$.
2. The associated no-signaling probability distributions $(p_{a,b|x,y})_{a \in [k], b \in [l]}$ admit an LHV model.
3. There exist a finite number of outcomes Λ , and appropriate maps Ψ_1, Ψ_2 such that the following diagram commutes:



Bell compression as factorization

Theorem

Let $\Phi : (CS_{k,g}^+)^* \rightarrow CS_{l,r}^+$ with $\Phi(\mathbb{1}_{CS_{k,g}^1}) \in CS_{l,r}^1$ and let $(V(K), V(K)^+, \mathbb{1}_K)$ be a GPT. Let Ψ and F be appropriate maps. Then, the following diagram commutes

$$\begin{array}{ccc} (CS_{k,g}^*)^+ & \xrightarrow{\Phi} & CS_{l,r}^+ \\ & \searrow \Psi \quad \nearrow F & \\ & V(K)^+ \otimes S_\Lambda^+ & \end{array}$$

if and only if the no-signaling probability distributions defining Φ satisfy

$$p_{a,b|x,y} = \sum_{\lambda \in [\Lambda]} w_\lambda \langle F_{b|y,\lambda}, q_{a|x,\lambda} \varrho_{a|x,\lambda} \rangle \quad \forall a \in [k], \forall b \in [l], \forall x \in [g], \forall y \in [r].$$

Here, $(w_\lambda)_{\lambda \in [\Lambda]}$ is a probability distribution, $(q_{a|x,\lambda})_{a \in [k]}$ are some conditional probability distributions, F is a multimeter, and $\{q_{a|x,\lambda}, \varrho_{a|x,\lambda}\}_{a \in [k], x \in [g]}$ is an assemblage for all $\lambda \in [\Lambda]$.

Bell compression in quantum mechanics

In quantum theory, we can find bipartite states $\varrho_{AB}^{(\lambda)}$ and a multimeter such that $q_{a|x,\lambda} \varrho_{a|x,\lambda} = \text{Tr}_A[(E_{a|x,\lambda} \otimes \mathbb{1}_B)\varrho_{AB}^{(\lambda)}]$. Thus, the equation on the previous slide can be written as

$$p_{a,b|x,y} = \sum_{\lambda=1}^{\Lambda} w_{\lambda} \text{Tr}[(E_{a|x,\lambda} \otimes F_{b|y,\lambda})\varrho_{AB}^{(\lambda)}] \quad \forall a \in [k], \forall b \in [l], \forall x \in [g], \forall y \in [r].$$

In GPTs, this might not be possible, depending on the bipartite theory.

Extendability of tensors

Extendability of tensors

Entanglement theory: ϱ_{AB} is **separable** if and only if for all $n \in \mathbb{N}$ there exists a state $\sigma_{AB_1B_2\dots B_n}$ that **extends** ϱ_{AB} , i.e.,

1. $\text{Tr}_{B_2\dots B_n}[\sigma_{AB_1B_2\dots B_n}] = \varrho_{AB}$
2. $\pi_{B_1B_2\dots B_n}(\sigma_{AB_1B_2\dots B_n}) = \sigma_{AB_1B_2\dots B_n}$, where π permutes $B_1, \dots, B_n$.

Thus, separability can be checked using the DPS hierarchy [DPS04].

To extend this idea to GPTs, we define a reduction map of n -th order:

$$\gamma_n^\Phi : V_B^{\otimes n} \rightarrow V_B, \quad \gamma_n^\Phi = \frac{1}{n} \sum_{i=1}^n \Phi^{\otimes i-1} \otimes \text{id} \otimes \Phi^{\otimes n-i},$$

Definition

Let Φ be a linear form in the interior of $(V_B^+)^*$. A tensor $\xi \in V_A^+ \hat{\otimes} V_B^+$ is n -extendable with respect to Φ if there exists $\xi^{(n)} \in V_A^+ \hat{\otimes} (V_B^+)^{\otimes n}$ such that $(\text{id} \otimes \gamma_n^\Phi)(\xi^{(n)}) = \xi$.

Definition

A multimeter $M = \{M_{\cdot|x}\}_{x \in [g]}$ is said to be n -wise compatible with $n \leq g$ if for all $\{x_1, \dots, x_n\} \subset [g]$ the measurements $\{M_{\cdot|x_i}\}_{i \in [n]}$ are compatible.

Theorem

Let $M : K \rightarrow CS_{k,g}^1$ be a multimeter and $\xi_M \in A(K)^+ \hat{\otimes} CS_{k,g}^+$ be the corresponding tensor. Then M is n -extendable with $\Phi = \mathbb{1}_{CS_{k,g}^1}$ if and only if it is n -wise compatible such that for all measurements $\{x_1, \dots, x_n\} \subset [g]$ there exists joint measurements $G^{(x_1, \dots, x_n)} = \{G_{a_1, \dots, a_n}^{(x_1, \dots, x_n)}\}_{a_1, \dots, a_n=1}^k$ which satisfy the following no-signaling constraints

$$\sum_{a_j=1}^k G_{a_1, \dots, a_n}^{(x_1, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n)} = \sum_{a_j=1}^k G_{a_1, \dots, a_n}^{(x_1, \dots, x_{i-1}, \tilde{x}_i, x_{i+1}, \dots, x_n)}$$

for all $a_j \in [k]$, $x_j \in [g]$, $j \in [n] \setminus \{i\}$ and $x_i, \tilde{x}_i \in [g]$ for all $i \in [n]$. In particular, M is compatible if and only if ξ_M is g -extendable.

Extendability of no-signaling behaviors

Definition

Let $g, r, k, l \in \mathbb{N}$ and $m \in [g]$ and $n \in [r]$. A no-signaling probability distribution $p = (p_{\cdot, \cdot | x, y})_{x \in [g], y \in [r]}$ on $[k] \times [l]$ has an (m, n) -LHV model if for all $(x_1, \dots, x_m) \subseteq [g]$ and $(y_1, \dots, y_n) \subseteq [r]$ the restricted no-signaling probability distribution $(p_{\cdot, \cdot | x, y})_{x \in \{x_1, \dots, x_m\}, y \in \{y_1, \dots, y_n\}}$ on $[k] \times [l]$ has an LHV model.

Note that $p = (p_{\cdot, \cdot | x, y})_{x \in [g], y \in [r]}$ has an LHV model if and only if it has an (g, r) -LHV model.

Theorem

Let $P \in CS_{k,g}^1 \hat{\otimes} CS_{k,g}^1$ with the corresponding no-signaling probability distribution $p = (p_{\cdot, \cdot | x, y})_{x, y \in [g]}$ on $[k] \times [k]$ and let $n \in [g]$. Then P is n -extendable if and only if p has an (g, n) -LHV model such that the corresponding (g, n) -LHV decompositions satisfy some additional no-signaling constraints. If $n = g$, then $P \in CS_{k,g}^1 \dot{\otimes} CS_{k,g}^1$.

Summary

- We have presented the formalism of general probabilistic theories (GPTs).
- In particular, we have seen how to write multimeters, i.e., collections of measurements, as channels from the state space to column stochastic matrices.
- We have used it to define measurement incompatibility for GPTs.
- We have expressed compatibility of measurements and different notions of simulations as factorizations of multimeters.
- We have then seen that the same ideas carry over to assemblages and no-signaling behaviors.
- We have seen that multimeters are n -extendable if and only if the measurements are n -wise compatible and the joint measurements satisfy no-signaling constraints.
- Likewise, we have seen that no-signaling behaviors are n -extendable if and only if they have a (g, n) -LHV model, satisfying some no-signaling constraints.

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